

**IN THE SPECIFICATION:**

Please amend the paragraph beginning on Page 5, line 7 as follows:

A1  
Referring to Fig. 2, the control section 200 performs a comprehensive control operation of the portable wireless terminal 100. A wireless section 202 controls transmission and reception of voice data and control data under a control of the control section 200. A voice processor 204 converts the voice data received by the wireless section 202 to an audible sound through a speaker SPK under a control of the control section 200, and outputs the same to make voice signals received from a microphone MIC as voice signals and outputs the voice signals to the wireless section 202. A key input section 206 comprising a number of numerical keys and functional keys mounted on a the key pad ~~100~~ 160 shown in Figs. 1A and 1B, as well as an automatic folder opening/closing key 180 mounted on one side surface of the main body 110, outputs the key input data corresponding to the keys pushed by the user to the control section 200. A display section 208 displays a variety of messages under control of the control section 200. A memory 230 comprises a program memory for storing program data required for controlling operation of the portable wireless terminal 100, and a data memory for storing data generated in the course of controlling or operating the portable wireless terminal 100 by the user.

Please amend the paragraph beginning on Page 11, line 11 as follows:

A2  
If the times of repeating operation of the motor are determined to be equal to the pre-set N in step 510, the control section 200 controls the sub-body 120 to be in the initial state, i.e., to be opened. The control section 200 allows opening of the sub-body 120 from the main body 110 by controlling the motor operating section 232 to rotate the motor 234 for opening/closing the sub-body 120 in a counter-clockwise direction, as indicated by step 512. In step 514 of Fig. 5, the control section 200 determines whether or not a signal sensing a complete opening of the sub-body 120 has been received from the open sensor 236. In the affirmative, the control section 200 proceeds with step 518 of Fig. 5 to cease operation of the motor 234 for opening/closing of the sub-body 120.